

1. The eigenvalues are 6, 4, and -1 . For $\lambda = 6$, the eigenvectors are of the form $x_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ (for any $x_1 \neq 0$), so one eigenvector would be $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. For $\lambda = 4$, the eigenvectors are of the form $x_3 \begin{bmatrix} -5/3 \\ 1/3 \\ 1 \end{bmatrix}$ (for $x_3 \neq 0$), so an eigenvector would be $\begin{bmatrix} -5 \\ 1 \\ 3 \end{bmatrix}$. Finally, the eigenvectors for $\lambda = -1$ have the form $x_3 \begin{bmatrix} 0 \\ -1/2 \\ 1 \end{bmatrix}$ (for $x_3 \neq 0$), so $\begin{bmatrix} 0 \\ 1 \\ -2 \end{bmatrix}$.

2. $[\mathbf{x}]_{\mathcal{B}} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$.

3. (a) The eigenvalue for $\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ is 2, the eigenvalue for $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ is 8 and the eigenvalue for $\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$ is 1.

(b) $P = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & -1 \\ 1 & 1 & 1 \end{bmatrix}$ and $D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 8 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

- (c) The eigenvalues of D are the same as the eigenvalues of A , since A and D are similar. The eigenvectors for $\lambda = 2$ are all vectors of the form $\begin{bmatrix} a \\ 0 \\ 0 \end{bmatrix}$, the eigenvectors for $\lambda = 8$ are of the form $\begin{bmatrix} 0 \\ a \\ 0 \end{bmatrix}$ and the eigenvectors for $\lambda = 1$ are of the form $\begin{bmatrix} 0 \\ 0 \\ a \end{bmatrix}$. In all cases, a is any non-zero real number.

4. (a) Since $\begin{bmatrix} -1 & 3 & 1 & 20 \\ 1 & 3 & 2 & 16 \\ 4 & 2 & 3 & 4 \end{bmatrix}$ is row-equivalent to $\begin{bmatrix} 1 & 0 & .5 & -2 \\ 0 & 1 & .5 & 6 \\ 0 & 0 & 0 & 0 \end{bmatrix}$, we see that the answer is yes, and that

$$\begin{bmatrix} 20 \\ 16 \\ 4 \end{bmatrix} = -2 \begin{bmatrix} -1 \\ 1 \\ 4 \end{bmatrix} + 6 \begin{bmatrix} 3 \\ 3 \\ 2 \end{bmatrix} + 0 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}.$$

- (b) No. Since the matrix whose columns are the vectors in \mathcal{B} does not row reduce to the identity (so does not have a pivot position in every row), there are vectors in \mathbb{R}^3 which are not linear combinations of the vectors in \mathcal{B} .

- (c) No. There is a free variable in the matrix whose columns are the vectors in \mathcal{B} . In fact, we see that $.5 \begin{bmatrix} -1 \\ 1 \\ 4 \end{bmatrix} + .5 \begin{bmatrix} 3 \\ 3 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$.

5. (a) T is NOT 1-1. This can be seen a variety of ways (the columns are not linearly independent, there is a free variable, or even the fact that there is no 1-1 linear transformation from \mathbb{R}^3 to \mathbb{R}^2). However, we can show explicitly that the map is not 1-1 by producing two vectors which get mapped to the same thing. Note that $\begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$ is a non-trivial vector in the null space of the matrix, so both it and the zero vector in \mathbb{R}^3 get mapped to the zero vector in \mathbb{R}^2 .

- (b) T is onto, since there is a pivot position in every row of the matrix. Thus the columns span \mathbb{R}^2 , so everything in \mathbb{R}^2 is a linear combination of the columns. That is, for every vector \mathbf{y} in \mathbb{R}^2 , there is a vector \mathbf{x} in \mathbb{R}^3 such that $T(\mathbf{x}) = \mathbf{y}$.

6. (a) Notice first that the vectors $\begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ -4 \\ 3 \end{bmatrix}$ are orthogonal, so we can use our formula for the projection. This gives

$$\text{proj}_W(\mathbf{y}) = \frac{39}{26} \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix} + \frac{25}{25} \begin{bmatrix} 0 \\ -4 \\ 3 \end{bmatrix} = \begin{bmatrix} 1.5 \\ 0.5 \\ 9 \end{bmatrix}.$$

(b) $\mathbf{y} = \begin{bmatrix} 1.5 \\ 0.5 \\ 9 \end{bmatrix} + \begin{bmatrix} 12.5 \\ -1.5 \\ -2 \end{bmatrix}.$

7. (a) A is row equivalent to $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

- (b)
1. A is invertable.
 2. $\det(A) \neq 0$.
 3. A has 3 pivot positions.
 4. $A\mathbf{x} = \mathbf{0}$ has only the trivial solution.
 5. $A\mathbf{x} = \mathbf{b}$ has at least one solution for each \mathbf{b} in \mathbb{R}^3 .
 6. The linear transformation $T(\mathbf{x}) = A\mathbf{x}$ is onto.
 7. The linear transformation $T(\mathbf{x}) = A\mathbf{x}$ is 1-1.
 8. $\text{Col}A = \mathbb{R}^3$.
 9. $\text{rank}A = 3$.
 10. $\text{Nul}A = \{\mathbf{0}\}$.
 11. $\dim \text{Nul}A = 0$.
 12. $\text{Row}A = \mathbb{R}^3$.
 13. The columns of A are linearly independent.
 14. The columns of A span \mathbb{R}^3 .
 15. The columns of A form a basis for \mathbb{R}^3 .
 16. A
 17. A^T is invertable.
 18. The number 0 is not an eigenvalue of A .